
1 (10 pts). Let

$$\mathbf{u} = \langle 3, -2, 1 \rangle \quad \mathbf{v} = \langle 0, 1, -2 \rangle \quad \mathbf{w} = \langle 2, 6, -3 \rangle$$

Find the following or state that they do not exist. If any of your answers is zero, carefully distinguish between the scalar 0 and the vector $\mathbf{0}$.

- a. $\mathbf{u} + 2\mathbf{v}$ b. $\mathbf{u} \cdot \mathbf{w}$ c. $\mathbf{w} \cdot \mathbf{w}$ d. the cosine of the angle between \mathbf{u} and \mathbf{w} .
e. $(\mathbf{u} \cdot \mathbf{v}) \cdot \mathbf{w}$ f. $\mathbf{u} \times \mathbf{v}$ g. $\mathbf{v} \times \mathbf{u}$ h. $\mathbf{v} \cdot (\mathbf{v} \times \mathbf{w})$
-

1. (Source: 12.2.22, 12.3.1, 12.3.5, 12.4.1, 12.4.13, 12.4.17)

a. $\mathbf{u} + 2\mathbf{v} = \langle 3, -2, 1 \rangle + 2\langle 0, 1, -2 \rangle = \langle 3, -2, 1 \rangle + \langle 0, 2, -4 \rangle = \langle 3, 0, -3 \rangle.$

b. $\mathbf{u} \cdot \mathbf{w} = \langle 3, -2, 1 \rangle \cdot \langle 2, 6, -3 \rangle = (3)(2) + (-2)(6) + (1)(-3) = -9.$

c. $\mathbf{w} \cdot \mathbf{w} = \langle 2, 6, -3 \rangle \cdot \langle 2, 6, -3 \rangle = 2^2 + 6^2 + (-3)^2 = 49.$

d. $\cos \theta = \frac{\mathbf{u} \cdot \mathbf{w}}{|\mathbf{u}||\mathbf{w}|} = \frac{-9}{\sqrt{\mathbf{u} \cdot \mathbf{u}}\sqrt{\mathbf{w} \cdot \mathbf{w}}} = \frac{-9}{7\sqrt{14}}.$

e. Does not exist. $\mathbf{u} \cdot \mathbf{v}$ is a scalar, which cannot be dotted with a vector.

f. $\mathbf{u} \times \mathbf{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 3 & -2 & 1 \\ 0 & 1 & -2 \end{vmatrix} = \mathbf{i} \begin{vmatrix} -2 & 1 \\ 1 & -2 \end{vmatrix} - \mathbf{j} \begin{vmatrix} 3 & 1 \\ 0 & -2 \end{vmatrix} + \mathbf{k} \begin{vmatrix} 3 & -2 \\ 0 & 1 \end{vmatrix}$
 $= ((-2)^2 - 1^2)\mathbf{i} - (3)(-2)\mathbf{j} + (3)(1)\mathbf{k} = \langle 3, 6, 3 \rangle$

g. $\mathbf{v} \times \mathbf{u} = -(\mathbf{u} \times \mathbf{v}) = -\langle 3, 6, 3 \rangle = \langle -3, -6, -3 \rangle$

h. $\mathbf{v} \cdot (\mathbf{v} \times \mathbf{w}) = (\text{the scalar}) 0$, since the vector $\mathbf{v} \times \mathbf{w}$ is orthogonal to \mathbf{v} (and to \mathbf{w}).